A Fair QoE-Aware MIMO Scheduling Scheme Based on Dynamic Latency Boundary for Non-Real-Time Service

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Abstract

In Multiple-input Multiple-output (MIMO) system, the scheduling schemes for guaranteeing quality of service (QoS) set fixed delay boundaries for data packets of special service. However, the utility function of the quality of user experience (QoE) is usually a continuous function mapping service latency to Mean Opinion Score (MOS). Based on a QoS provisioning scheme, we propose a QoE-aware scheduling scheme with dynamic latency boundary. We also propose a weight function, which is a logarithmic function of the mean opinion score (MOS) level, to guarantee fairness. Numerical results indicate that the proposed scheme achieves higher performance from the view of user experience and fairness. This scheme can be deployed in commercial networks because of its low computational complexity.

Keywords: Multiple-input/multiple-output (MIMO), quality-of-service (QoS), quality-of-experience (QoE), non-real-time service

1. Introduction

The non-real-time data services, such as web, social network service, http progress video, and instant messaging, have become more and more popular in mobile networks. This trend motivated telecom operators and equipment providers to design new scheduling strategies for guaranteeing the quality of user experience (QoE) and saving resources [1], [2], [3]. They deployed Content Distribution Networks (CDN) in mobile networks to reduce the latency in the core network. To decrease the capacity gap between the air interface and the core network, the Multiple-Input Multiple-Output (MIMO) technique has been applied to improve stability and the rate of wireless transmission. J.-B. Landre assessed this technique in realistic environments [4], [5], and S. Parkvall and A. Farajidana performed their test in a real, operational network [6], [7]. These tests demonstrate their commercial worth; however, MIMO also increases the complexity of the coding and scheduling.

Considerable studies have been focused on throughput capacity and quality-of-service (QoS) of MIMO systems. G. Caire, P. Viswanath, S. Vishwanath and H. Weingarten have characterized the capacity region of the Gaussian MIMO broadcast channel and proposed nonlinear scheduling schemes to maximize throughput, respectively [8]-[11]. T. Yoo proposed the “zero forcing beamforming” (ZFBF) scheme with lower time complexity [12]. To meet the packet delay requirements of different services, some QoS scheduling schemes have been proposed. D. Wu proposed the concept of “effective capacity” for mapping the throughput capacity to the QoS capacity [13]. J. Tang explored the trade-off between throughput and QoS provisioning through “effective capacity” and applied it into the MIMO system [14], [15]. Moreover, based on game theory, L. Zhong gave the optimal solution of throughput under delay and power constraints [16].

However, these schemes meet some challenges in commercial networks with non-real-time data services. First, because the function bridging the latency and the QoE is continuous, we cannot set a fixed delay boundary for data service packets. Next, many mobile network operators put all of the small data flow services into a common channel to save wireless resources. As the number of users increases, the base station (BS) cannot afford large time consumption for scheduling. Finally, a non-real time service might require a large number of time slots; the scheme needs to adapt to the variations in the channels and services.

In this paper, we propose a QoE-aware scheme based on a QoS scheme. We map the different QoE levels to the latency boundaries and adjust the expected QoE level according to the state of the service and the channel. The numerical results show that the proposed scheme results in higher average performance and fairness from the view of QoE with low computational complexity.

The rest of the paper is organized as follows: Section 2 describes the system model and the objective function from the view of user experience. Section 3 introduces the traditional schemes and the proposed schemes. Section 4 presents simulations and compares the effectiveness of the four schemes. The paper’s conclusions are presented in section 5.

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2. System Model

We consider a MIMO system with \( N_t \) transmission antennas serving multiple users. The base station (BS) puts all of the non real time data services into one common channel, and each user has only one data service and uses one antenna. The type of service is web or short video. We assume that “Deep Packet Inspection” (DPI) can obtain perfect state information of the services, such as the service type, total size of the data flow.

2.1 MIMO System Model

We assume that the length of the time slot is smaller than that of the channel coherent time. Therefore, the signal received by user \( k \) can be given by

\[
y_k = h_k v_k \sqrt{p_k s_k} + \sum_{j \neq k} h_k v_j \sqrt{p_j s_j} + n_k
\]

(1)

Where \( s_k \) is the data, \( h_k \in C^{n \times 1} \) is the channel gain, \( v_j = R^{N_s \times n} \) is the steering vector, \( p_k \) is the allocated power, \( n_i \) is the Gaussian noise with variance \( E[n_i n_i^*] = \sigma^2 \), and the term marked with interference is the in-cell interference. The Signal-Interference-plus-Noise-Ratio (SINR) can be given by

\[
SINR_k = \frac{p_k |h_k v_k|^2}{\sum_{j \neq k} p_j |h_k v_j|^2 + \sigma^2}
\]

(2)

with perfect CSIT, the rate of user \( k \) can be given by

\[
r_k = \log_2 \left( 1 + SINR_k \right) \times \text{band}
\]

(3)

2.2 QoE of non-real-time Data Service

The “Mean Opinion Score” (MOS) is used to obtain the human user’s view of the quality of service. This concept originated from voice tests [17]. The MOS of the data service can be obtained using some objective measurement methods formulated by the latency function [18]. The problem of maximizing the sum of the MOS of the users can be formulated as

\[
\max_{\mathbf{x}} \sum_{i=1}^{K} U_i (D_i)
\]

(4)

Where \( U_i \) is the utility function of user \( k \) to obtain a MOS depending on the service type and \( D_i \) is the latency. For a current time slot, \( D_i \) can be given by

\[
D_i = L \times \left( \text{Past}_i + F_i \right)
\]

(5)

Where \( L \) is the duration of each time slot, \( \text{Past}_i \) is the elapsed time from the beginning of the application, \( F_i \) is the estimated buffering time for the remaining data.

2.3 Traffic Model

Many scheduling schemes are performed using real-time traffic models or full buffer models characterized by a constant number of users and unlimited amounts of data flow for each user [19]. We adopt a full buffer model but with limited data in each data flow. We assume that the length of the data flow of each service is finite and services will stop after the reception is completed. Users might start new services after one service finishes. Moreover, the rate of the core network is faster than that of the air interface transmission. Therefore, the BS does not have to wait for the data from the remote server.

3. MIMO Scheduling Scheme for QoE

In this section we will give a brief review of “dirty paper code” (DPC) for MIMO systems and QoS schemes and describe the proposed QoE-aware scheme based on existing QoS schemes.

3.1 Review of ZF-DPC

The scheduling scheme called ranked known interference (RKI) is proposed for MIMO systems in reference [8]; this scheme is also known as zero force dirty paper code (ZF-DPC). ZF-DPC is an iterative scheme to obtain suboptimal throughput. Each iteration, the candidate users are appended to the sequence of selected users and the scheme applies Gram-Schmidt orthogonalization to the channel matrix. The candidate user with the highest SINR is selected. The time complexity of the scheme will increase sharply as the number of users increases. Moreover, the fairness of this scheme is very low.

This scheme needs \( \left( N_s^2 \times K - N_s \times K \right) / 2 - (K-1)N_s / (2N_s - 1) / 6 \) projections for user selection. Therefore, the time complexity of the algorithm is \( O(N_s K) \), if \( N \) is treated as a constant, the time complexity is \( O(K) \), where \( K \) is the number of users and \( N_s \) is number of transmit antennas.

3.2 Review of the QoS Scheme Based on Game Theory

G. Song proposed a resource allocation method based on a gradient of the utility function with respect to the rate [19]. This method was used to explore the trade-off between QoS requirements and system throughput by L. Xingmin [20]. Based on the research results of [20], L. Zhong proposed a game theoretic QoS model in MIMO system for real time service [16]. The delay boundaries are modeled into weights using the “Nash Bargaining Solution” (NBS). Under the premise of meeting the latency constraint, the QoS-guaranteeing algorithm minimizes the delay for each user. The objective function is

\[
\max_{\mathbf{x}} \sum_{i=1}^{K} \ln \left( D_i - q_i / r_i \right)
\]

(6)

Where \( r_i \) is the possible rate combination, \( D_i \) is the latency boundary, and \( q_i \) is the length of the buffering queue data. This expression is equivalent to

\[
\max_{\mathbf{x}} \sum_{i=1}^{K} \ln \left( D_i - q_i / r_i \right)
\]

(7)

Defining \( U_i = \sum_{i=1}^{K} \ln \left( D_i - q_i / r_i \right) \), the solution can be found from the maximum value of

\[
\nabla U_i (t-1) \cdot \tilde{r}(t)
\]

(8)
where \( U_i(t) = \sum_{r=1}^{t} \ln \left( D_i - q_i / r_i \right) \),
\( \tilde{r}(i) = \{r(i)_1, r(i)_2, \ldots, r(i)_i \} \), and \( \forall U_i \) is gradient of \( U_i \). The gradient can be written as
\[
\frac{\partial U_i}{\partial r_k} = \frac{q_i}{D_i r_k - q_i r_k - r_k} = \frac{q_i}{D_i r_k - q_i r_k}. \quad (9)
\]

Because the ratio among \( \tilde{r}(i) \) is equal to the ratio of \( \forall U_i \), the objective function determines the maximum value.

3.3 QoE-Oriented Scheme Based on Dynamic Latency Boundary

Due to the problems mentioned in section 1, we propose a scheme transforming the QoE problem to a QoS problem by setting the latency boundaries for different MOS levels. The scheme computes the latency requirements corresponding to each integral number of MOS, that is, MOS = 1, 2, 3 or 4, for each user, and then selects an achievable MOS level for the latency boundary according to the state of the channel and the services. Finally, the scheme selects \( N_i \) users with the largest values of expression (9) and allocates the power iteratively to let the rate ratio of the users approach the gradient. Because this algorithm has no QR-decomposition for selecting users, the time complexity is unrelated to the number of users. According to the expression (4) (5) and (9), the objective function can be rewritten as:
\[
\alpha \cdot \frac{q_i}{\left( U_i^m(MOS_i) - Past_i \right) \cdot r_i - q_i r_i}. \quad (10)
\]

Where \( U_i^m() \) maps the MOS to the latency requirement, \( MOS_i \) is the achievable MOS level for user \( k \). For fairness, let \( \alpha = \ln(5/MOS_i) \); therefore, a user with a lower achievable QoE level obtains a higher priority. The steps of the scheme are followed as shown:

1) Initialize \( S = \{ \}, H_{k, v}, \) pieces = 100,
2) For \( k = 1, \ldots, K \),
3) AchievableRate \((k) = f(\text{band}, \text{SNR}, H(k))\)
   (f() returns the achievable rate if user \( k \) get all power)
4) END FOR
5) For \( k = 1, \ldots, K \),
6) MOS = 5,
7) REPEAT
8) \( D_s = \text{DelayBound}_i(MOS_i) - \text{ConsumedTime}(k) \)
   (DelayBound() give the delay requirement to MOS)
9) UNTIL \( D \cdot \text{AchievableRate}(k) - \text{Buffering}(k) > 0 || \text{MOS} < 1 \)
10) IF MOS < 1
11) \( \text{gains}(k) = 0 \)
12) ELSE
13) \( \text{gains}(k) = \frac{\ln(5/MOS_i) \cdot \text{Buffering}(k)}{D_i^m - \text{Buffering}(k) \cdot \text{AchievableRate}(k)} \)
14) ENDIF
15) ENDREPEAT
16) \( \text{Put largest gains}(k) \) into \( S \)
17) FOR \( i = 1, \ldots, |S| \),
18) \( \text{ENDFOR} \)

4. Simulation Result

In this section, we simulated a non-real-time service traffic scenario and an urban wireless scenario to evaluate the performances of the ZF-DPC, QoS and QoE schemes. Many other simulations were performed using real-time traffic models or full buffer models characterized by a constant number of users and unlimited amount of data flow for each user [21]. In our simulation, we adopt a more practical traffic model in which the length of the data flow is finite and the number of users is also constant, which means that each user will start new a service after the reception of the current service completes. Moreover, we suppose the transmit rate of the core network is much faster than the air interface transmission, that is, the BS does not have to wait the data from remote servers. Therefore, we do not need to consider the data arriving rates in the BS.

In our simulation, we consider a BS with four transmitting antennas servicing multiple users with one antenna. The distances between the BS and users are distributed between 30 m and 500 m. The other parameters are listed in Table 1.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>cell radius</td>
<td>500 m</td>
</tr>
<tr>
<td>system bandwidth</td>
<td>40 MHz</td>
</tr>
<tr>
<td>noise density</td>
<td>-174 dBM/HZ</td>
</tr>
<tr>
<td>speed of users</td>
<td>1 m/s</td>
</tr>
<tr>
<td>duration of slot</td>
<td>10 ms</td>
</tr>
<tr>
<td>total power</td>
<td>40 W</td>
</tr>
<tr>
<td>path loss</td>
<td>34.53 + 38 log10(D)</td>
</tr>
<tr>
<td>size of video</td>
<td>10–20 Mbits</td>
</tr>
<tr>
<td>size of web page</td>
<td>0.5–2.5 Mbits</td>
</tr>
</tbody>
</table>

The types of services include web and short video. The short video starts to play after the reception finishes. The web services are separated into small web page and large web page according to the maximum latency users expect. The number of users ranges from ten to seventy. After one service is completed, the user starts a new service. The simulation lasts one hundred seconds, that is, ten thousand
time slots. According to the type of service, we map latency to the user experience.

In this simulation, we adopt the QoE utility function recommended by [18] to measure the web service:

$$MOS = \frac{4 \cdot (\ln(D) - \ln(0.005 \cdot \text{Max} + 0.24))}{\ln((0.005 \cdot \text{Max} + 0.24)/\text{Max})} + 5 \quad (11)$$

Where $\text{Max}$ is the maximum latency users expect, which is set to 30 s and 60 s for small and large web pages, and $D$ is the actual latency. The utility function is proposed by T. Hossfeld in [22]:

$$-1.577 \cdot \ln(D + 0.742) + 5 \quad (12)$$

In our simulation, we examine the average MOS of the schemes. The value can be given by

$$\sum_{i=1}^{K} \frac{\text{MOS}_i}{K} \quad (13)$$

Where $K$ is the total number of users, $\text{MOS}_i$ is the average MOS of user $i$, and the MOS of each user is the average MOS of all services triggered by this user, which is equal to:

$$\text{MOS}_i = \frac{1}{|U_i|} \sum_{j \in U_i} \text{MOS}_j \quad (14)$$

Where $|U_i|$ is the set of services completed by user $i$, $\text{MOS}_j$ is the Mean Opinion Score of service $j$ in this set.

Another index we adopted is Jain’s Fairness Index (FI) [23]. The FI is given by:

$$\text{FI} = \frac{(\sum_{i=1}^{K} \text{Index}_i)^2}{(K \cdot \sum_{i=1}^{K} \text{Index}_i^2)} \quad (15)$$

Where $\text{Index}_i$ is the MOS of user $k$ or the number of services completed by user $k$.

Fig. 1 plots the values calculated using expression (13) of the three schemes with the number of users ranging from 5 to 70. Because of the high time complexity of ZF-DPC, we only give the results of ZF-DPC using 5 to 40 users. Fig. 1 shows that the average MOS of the scheme with dynamic latency boundary only experiences a slow decline as the number of users increases; its performance is higher than that of the original QoS provisioning scheme. The performance of ZF-DPC, which has the greatest computational complexity, drops sharply.

Jain’s fairness index for the average MOS of the users is illustrated in Fig. 2. The results show that the fairness of our proposed scheme experiences no decline as the number of users increases, while the performances of the other two schemes drop significantly. Fig. 3 shows Jain’s fairness index for the services completed by each user. The proposed QoE scheme also achieves better fairness, while the original QoS scheme has the worst performance in the three schemes.

The simulation results show that the proposed QoE-aware scheme achieves better QoE fairness because it can adjust the latency boundary according to the user experience and the changing environment. The original QoS scheme cannot adjust the latency boundary during non-real-time service; thus, it cannot adapt and cannot give different priorities to users with different MOS levels. The defects in ZF-DPC are its high computational complexity and lack of QoE recognition.

5. Conclusions

We examined three transmission strategies for non-real-time data services in MIMO systems considering QoE fairness. The results showed that the QoE scheduling scheme based on dynamic latency boundary can achieve better average MOS and fairness because our proposed scheme can adjust the latency boundaries according to the state of the channel and the services. The time complexity of this scheme is much lower than traditional schemes because it does not consider channel correlation among users in user selection phase. In this paper, we investigated the schemes with perfect channel state information at the transmitter (CSIT). The case of imperfect CSIT will be an extension of this work.

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